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Universiteit Utrecht

Introduction

The characterization and localization of subgrain boundaries (sGB) in typically coarse-grained polar ice requires good correlation of light microscopy (LM) and EBSD mapping, which needs a stable sample surface avoiding alteration by (e.g.) sublimation during the measurement.

Sample Transfer



exposed to warm

rod by a movable stage

tip of transfer rod alum Cryo-transfer system. (a) Transfer



aluminium stub





Sample Surface



After transfer: irregular layer of frost crystals with cauliflower morphology (Zone 1 of structure zone model for growth of ice films; Cartwright EA,2010).

Cauliflower frost after transfer is removed by controlled sublimation in the prep. chamber leading to surface

The sample is never

atmosphere air

during transfer.

nitrogen gas). (b) Transfer rod



faceting. Sublimation is carried out before exposition to ebeam, which changes sublimation/condensation behavior.

Influence of beam exposure to surface topography. Sample was subllimed after area scanning. (a) Areas exposed to e-beam clearly stand out as squares (left: 20 min @ 10 kV, right: 30 min @ 10 kV). (b) Detail of (a) showing preexposed areas and the only sublimed surface (band in middle).

References:

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Baker et al., 2007, Microstructural characterization of firn. Hydrol. Process., 21, 1624-1629. Andreas, 2007, New estimates for the sublimation rate for ice on the Moon. Icarus, 186, 24-30.

Obbard et al. 2006, Using electron backscatter diffraction patterns to examine recrystallization in polar ice sheets. J. Glaciol., 52, 546-557. Kipfstuhl et al. 2006, Microstructure mapping: a new method for imaging deformation induced microstructural features of ice on the grain scale. J. Glaciol., 52, 398-406.



EBSPs with focused and defocused beam. (a)–(d) High P conditions using N₂ gas. (e)–(h) Low P conditions. Acc. voltage, time/frame for pattern collection, chamber P and T given. Mapping step size 5 µm, grid size 10×10. Values for defocus, where noted, given.

Cryogenic EBSD: a technique to preserve a stable surface in a low pressure SEM to characterize ice microstructure I. Weikusat (ilka.weikusat@awi.de), D.A.M. De Winter, G. M. Pennock, M. Hayles, C.T.W.M. Schneijdenberg, M. R. Drury

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SEM & EBSD Conditions



SEM chamber pressure (P) and temperature (T) conditions chosen within the ice stability P-T-field enable the preservation of a stable surface for good correlation with LM. Instead of sublimation, beam defocus is used as charge minimizer. EBSP quality and grid distortion can be improved significantly. Defocusing changes the spatial resolution slightly, which is however still far below the scales of the envisaged substructres.



🏹 (a) & (b) Faceted surfaces after sublimation. Faceting depends on crystal orienta-(c)-(e) EBSPs from grains in (a) resp.



Equilibrium phase diagram (P-T) of stability conditions for ice and ice in equilibrium with water vapour in a closed system (after Andreas, 2007). SEM chamber P and stage T conditions of published EBSD studies on ice shown as blocks: (PMB=Piazolo EA, 2008; BOIM=Baker EA,2007; OBS=Obbard EA, 2006). Typical SEM chamber P and T conditions examined here (Weikusat EA,2010) shown as circles. Equilibrium Tequ for chamber P of 10⁻⁶ hPa is ca. -112°C (shown). Partial vapour Pequ (shown) for a lower stage temperature of -150°C is much lower than the chamber P.



Grid of damage spots, caused by e-beam. EBSD map settings identical: 10 kV acc. voltage, 40ms/frame for pattern collection, 1.4×10⁻⁵ hPa chamber P, -103°C chamber T. Distortion of grid is significantly less in (b). Note, 5 µm step size as set, is actually slightly changed giving a slightly larger spot distance in (b). Accurate resolution and scale for maps has to be determined from an SE image taken after the mapping.





Locating region of interest in the SEM (sample B37, 93.9 m depth). (a) showing boundary and pore features (Kipfstuhl EA,2006). (b) corresponding area indicated as circle in (a). Most grains have the same shape: one boundary (arrowed) has slightly altered position.

EBSD and LM mapped microstructure (sample EDML Localization of relevant features, 2575.8m depth). (a) Map after replacement of some nonindexed pixels and all misindexed pixels. Etched GB is poorly demanding esp. in very coarseindexed. Lower grain shows a slight orientation gradient. grained deep ice, is enabled by pre-(b) After orientation averaging (2 passes of 3×3 filter) most low angle noise is removed to show sGB penetrating several scanning with LM microstructure 100s of µm into the core of the grain. Filtering removes low angle misorientation noise but also creates a low angle bounmapping. Comparison with these dary artefact (arrow). (c) After orientation averaging (2 pasetch features allows orientation aver- ses of 5×5 filter) boundaries of 0.2-0.5° are also artefacts of the orientations averaging filter. Angular resolution is ca. 0.7° aging as noise reduction method. after orientation averaging. (d) Corresponding etched LM μ S. Correlation of LM with EBSD microstructure is excellent.

Characterization EBSD analysis (sample EDML 655.9 m depth). (a) Map with subsets along sGB highlighted. sGB types are labelled 1–3. (b) Stereographic projections of c- and <-12-18)--a-axes. (c) Rotation axes among neighbouring pixels with misorientation >0.5° in sGB subsets. Labels 1–3 Sample Y axis (core axis) in crystal coordin correspond to labels in (a). (d) Simplified interpretation (following Weikusat EA,2011). 0 μm; BC+IPF+GB; Step=10 μm; Grid100x4 'UJJ

sGB can be characterized: (1) tilt boundaries comprised of edge dislocations gliding in basal plane, (2) twist boundaries built by basal screw dislocation sets and (3) tilt boundaries comprised of edge dislocations gliding on nonbasal planes.

Spatial resolutions depend on exact P-T conditions. They are between 0.5 and 3 µm. Substructure spacing is typically above 10 µm.

Sequential EBSPs across vertical GB. Slightly defocused beam. (a) High P.Two images (#154 – 155) show bands from both patterns of neighbouring grains. (b) Low P. Three images (#34–36) show bands from both patterns . (c) Low P. Three images (#154 – 155) show bands from both patterns.

Excellent reproducibility of structures, orientations and indexing can be achieved if sublimation/con- $\sum_{i=1}^{2} \frac{1}{i}$ densation is minimized (see also Sample Surface).

EBSD mappping reproducibility (sample EDML 2575.8 m depth). (a) EBSD map (step size 10 µm) (b) second EBSD map of same area (step size 1 µm). Indexing was 87% and 88% resp. (without offline reanalysis). (c) Stereographic projection of data in (a). (d) Stereographic projection of data in (b). Acc. voltage 10 kV. Noise reduction of both maps was made by replacement of some nonindexed pixels and all misindexed pixels and one pass of a 3×3 modified Kuwahara filter.

EBSD & LM Correlation



legend />0.2°/>0.5°/>0.7°/>1°/>10°

Example for Substructure

