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# The HBM-PDAF assimilation system

#### for operational forecasts in the North and Baltic Seas

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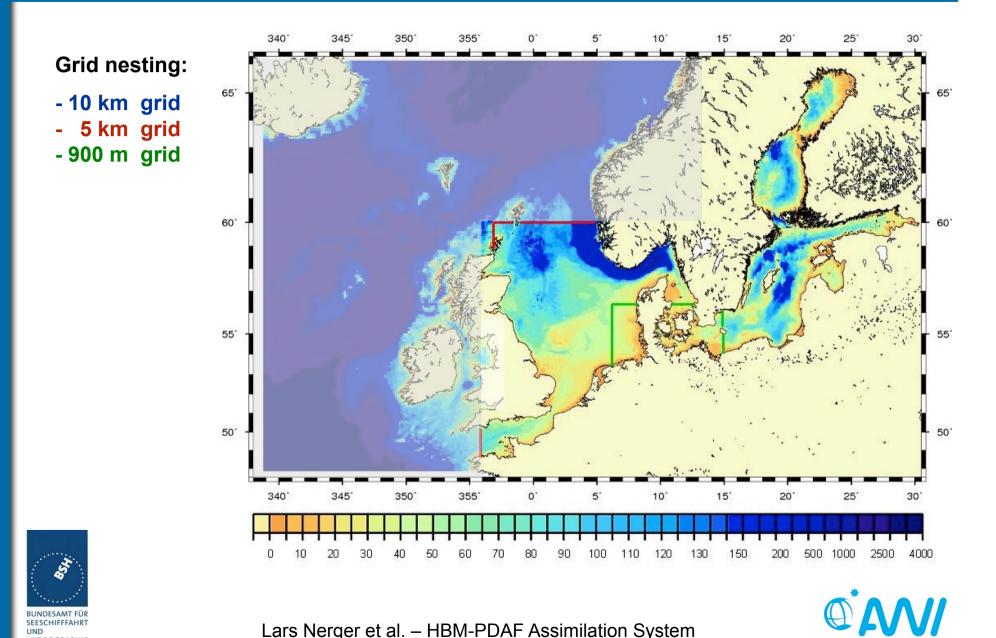


BUNDESAMT FÜR SEESCHIFFFAHRT UND HYDROGRAPHIE





# Starting point: Operational BSH Model (BSHcmod), V4

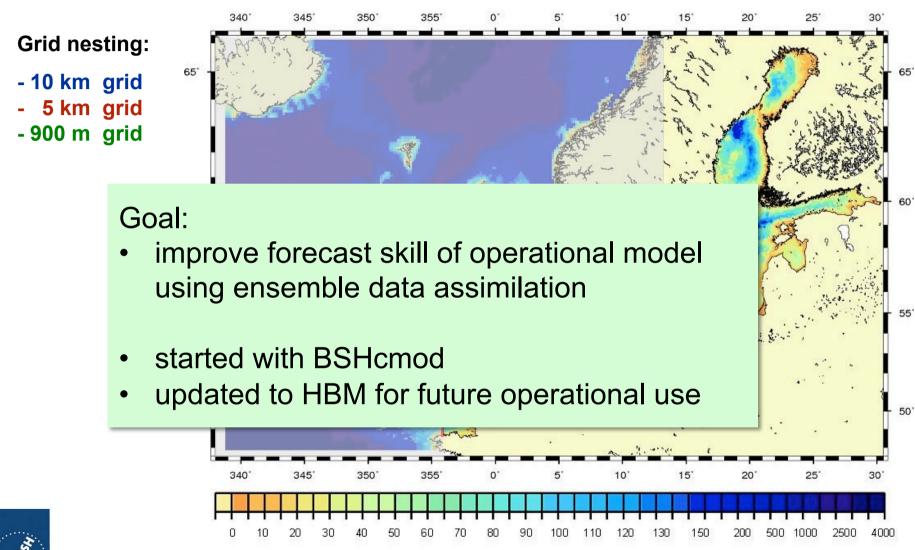


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# Starting point: Operational BSH Model (BSHcmod), V4





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# Logical separation of assimilation system PDA

single Filter program Initialization analysis state state re-initialization time observations Core of PDAF Model **Observations** mesh data initialization obs. vector obs. operator time integration post processing obs. error

- → Explicit interface
- Indirect exchange (module/common)



HYDROGRAPHIE

Nerger, L., Hiller, W. Software for Ensemble-based DA Systems – Implementation and Scalability. Computers and Geosciences. 55 (2013) 110-118



Parallel

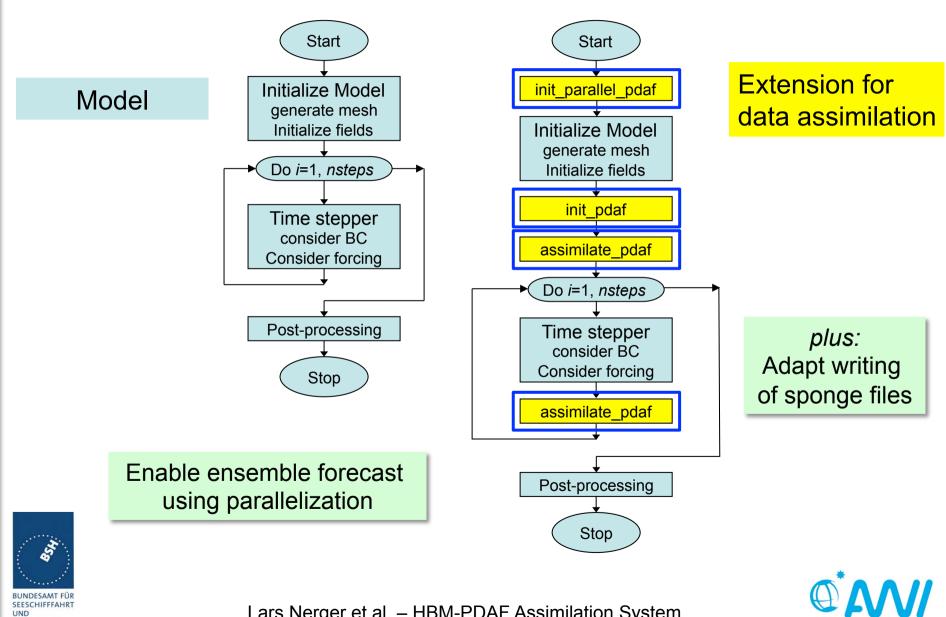
Assimilation Framework

Data

### **Extending a Model for Data Assimilation**

Parallel Data Assimilation Framework

PDA



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DAF Parallel Data Assimilation Framework

- Model and observation specific operations
- Elementary subroutines implemented like model routines
- Called by PDAF routines through a defined interface

Link to model

- initialize model fields from state vector
- initialize state vector from model fields

**Observation handling** 

- application of observation operator H to some vector
- initialization of vector of observations
- multiplication with observation error covariance matrix





DAF Parallel Data Assimilation Framework

PDAF - Parallel Data Assimilation Framework

- provide support for ensemble forecasts
- provide fully-implemented filter algorithms
- easily useable with (probably) any numerical model (coupled also to NEMO, MITgcm, FESOM, ADCIRC)
- makes good use of supercomputers
- separate development of model and assimilation algorithms

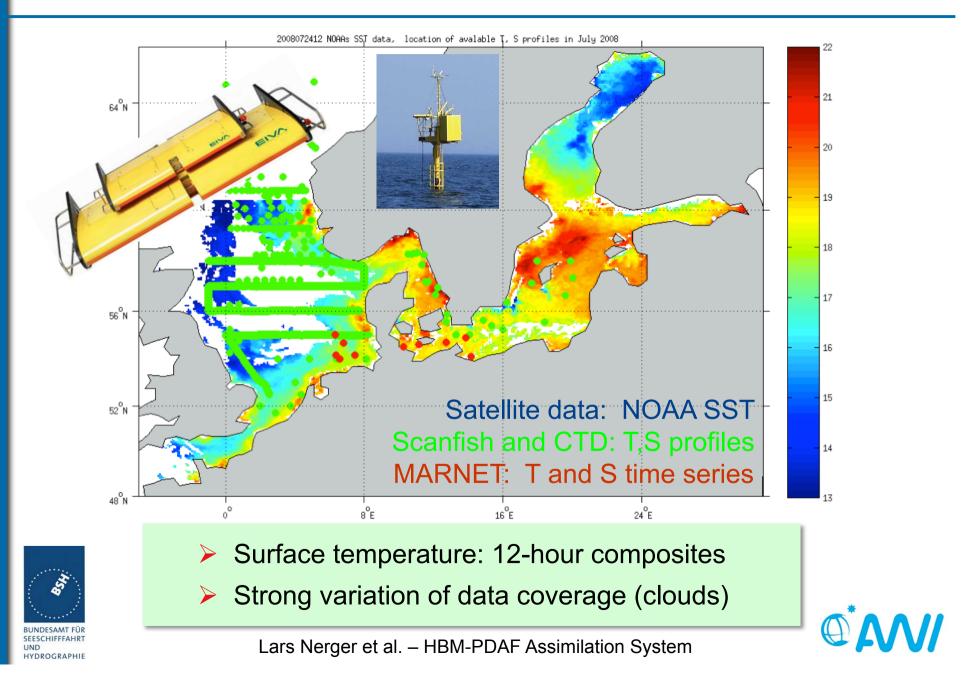
Open source: Code and documentation available at

http://pdaf.awi.de





#### **Assimilated Data – Satellite, MARNET and profiles**



# **Assimilation Methodology**

- 12-hour forecast/analysis cycles
- Ensemble size 8 (sufficient for good results)
- Assumed data errors:

SST: 0.8°C (gave best results)

MARNET: 0.5°C, 0.5 psu

Scanfish: 0.8°C, 0.5 psu

- Ensemble Kalman filter (local SEIK)
- Localization:
  - Influence radius 100 km (tuned)
  - Weight on data errors (Exponential, e-folding at 100 km)

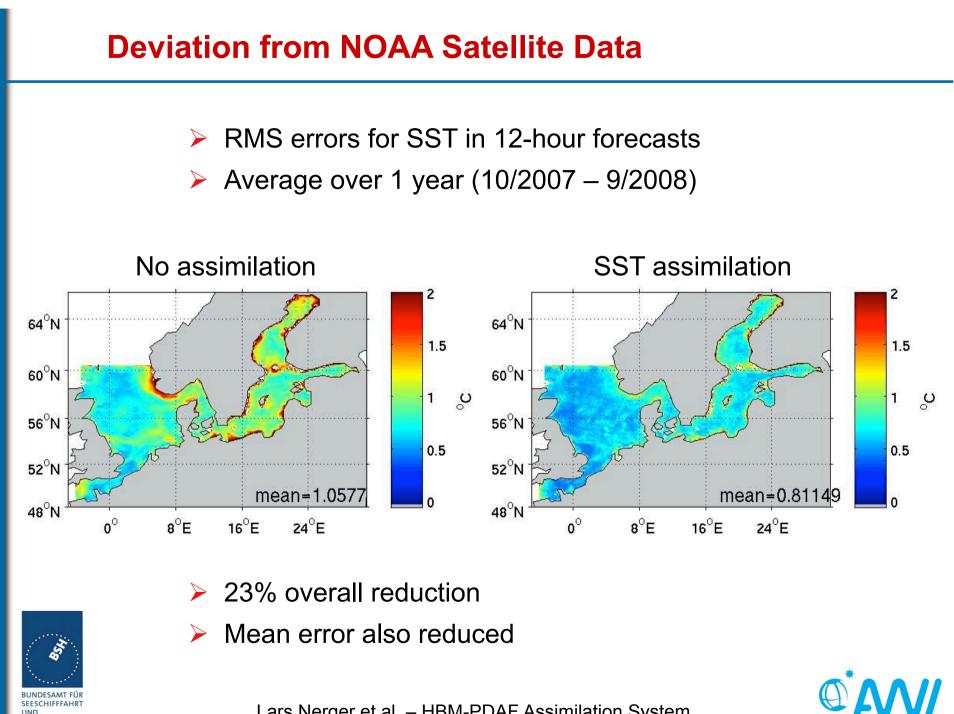
Showing mainly results from BSHcmod

(very similar to HBM)



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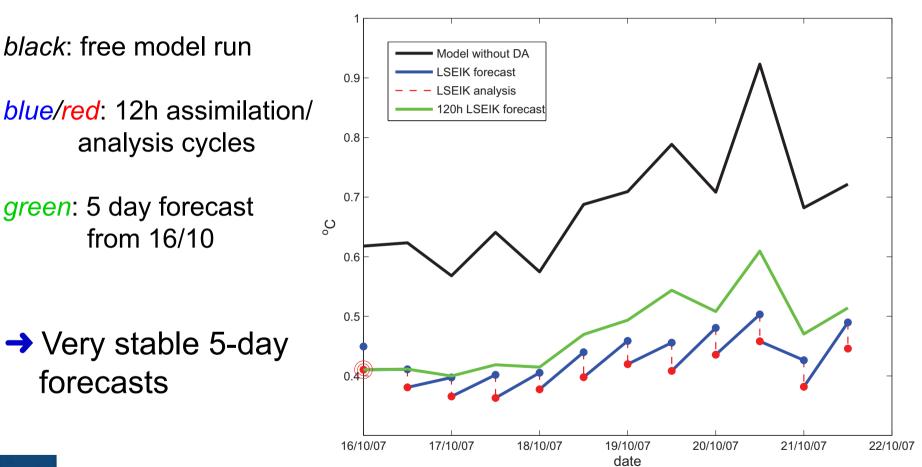




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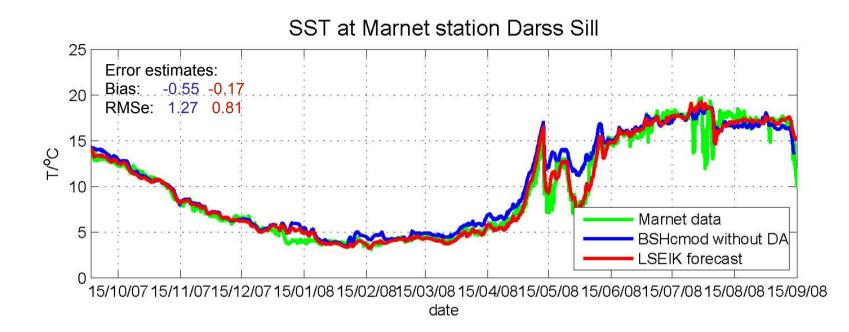
### **Forecast improvements**



RMS error for SST over time



# Validation with independent data (only SST assim.)



#### MARNET station data

- Reduction of
  - Bias
  - RMS error

#### 1 year mean over 6 stations:

	RMSe	bias
free	0.87	0.3
satellite data	0.59	0.11
assimilation	0.55	0.08



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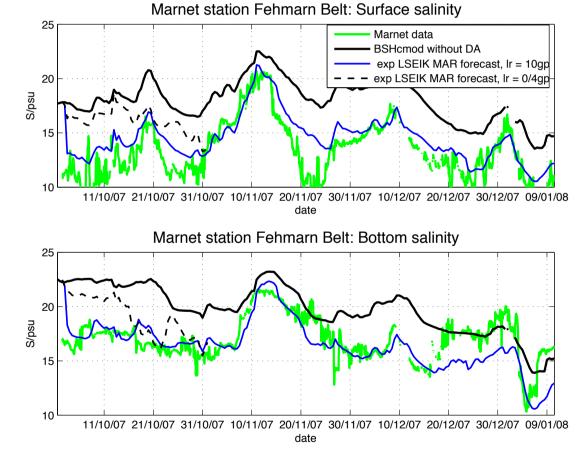
#### Red: Assimilation 12h forecasts



# **Assimilation of MARNET data**



- Salinity: Significant improvement at surface and bottom
- Localization parameters influence assimilation performance









# Summary

- HBM-PDAF system provides improved forecasts
- Very small increase of run time
- Assimilation framework PDAF to implement assimilation systems (http://pdaf.awi.de)

### Ongoing work

- Include coastal mesh for assim. (900m resolution)
- Include ecosystem model ERGOM (@BSH)
- Assimilation of clorophyll data
- Switch to ESTKF filter (Nerger et al., MWR, 2012)



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#### References

Nerger, L., Hiller, W. (2013) Software for Ensemble-based Data Assimilation Systems – Implementation and Scalability. *Computers and Geosciences*. 55, 110-118

Losa, S.N. et al. (2012). Assimilating NOAA SST data into the BSH operational circulation model for the North and Baltic Seas: Inference about the data. *Journal of Marine Systems*, 105-108, pp. 152-162

Losa, S. N. et al. (2014). Assimilating NOAA SST data into the BSH operational circulation model for the North and Baltic Seas: Part 2. Sensitivity of the forecast's skill to the prior model error statistics. *Journal of Marine Systems*, 129, 259-270



