

Recent lidar measurements from AWIPEV

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Aims aerosol:

(remote sensing sun/star-photometer, Raman lidar) Continue long-term measurements Participate in aerosol closure experiments

... from aerosol to clouds

Aims BL:

Understand micrometeorol. influences on BL properties Understand coupling between local and synoptic processes

... linkage aerosol to BL ...





- Continuous instruments during campaign: wind lidar (50m / 10min, from ± 150 – 1000m), 3-D wind BSRN station: T, p, rh, wind, short – long-wave up and down
 - radiometer (T: 50 -2000m, 20min, approx 100m resolution, humidity (same resolution, quality?) photometers at village & Zeppelin station (if sunny)

Vaisala CL51 Ceilometer (910nm)

• Sporadic instruments:

radiosonde (11UT each day) KARL lidar (clear sky)





PI: Masataka Shiobara from NIPR (Tokyo)

Sky radiometer (photometer + 2 channels around 1.5µm) – many years starting in April

Depolar. resolved MPL lidar

(all sky camera) -All continuous

Yutaka Kondo: Univ Tokyo, BC since 2012





no major flaw in data detailed analysis to be done KARL: 30 March – April 6 most interesting air trajectories not easy

Ceilometer: backscatter up to 1000m Master thesis \rightarrow connection to Iwona

Wish:

Paper on event and / or paper on season AWI: meteorology, remote sensing

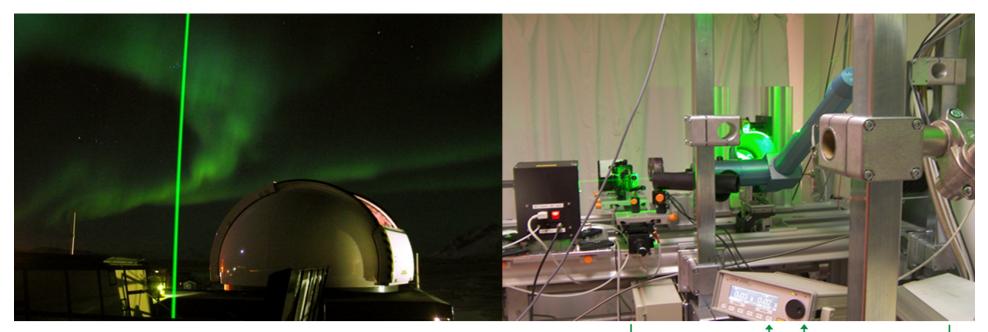


Currently 3 lidars from AWI:

- a) Koldewey aerosol Raman lidar (KARL), since 2001
- b) a wind lidar (Leosphere) since Dec. 2012
- c) different ceilometers (Vaisala), one each time, quasi continuously since 2001

Status of instruments Recent data Discuss abilities, shortcomings

Aim: invite you to develop strategy how to use these instruments for common, future projects, espec. for clouds!



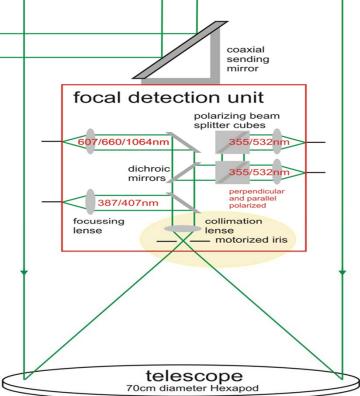
a) Koldewey Aerosol Raman Lidar (KARL)

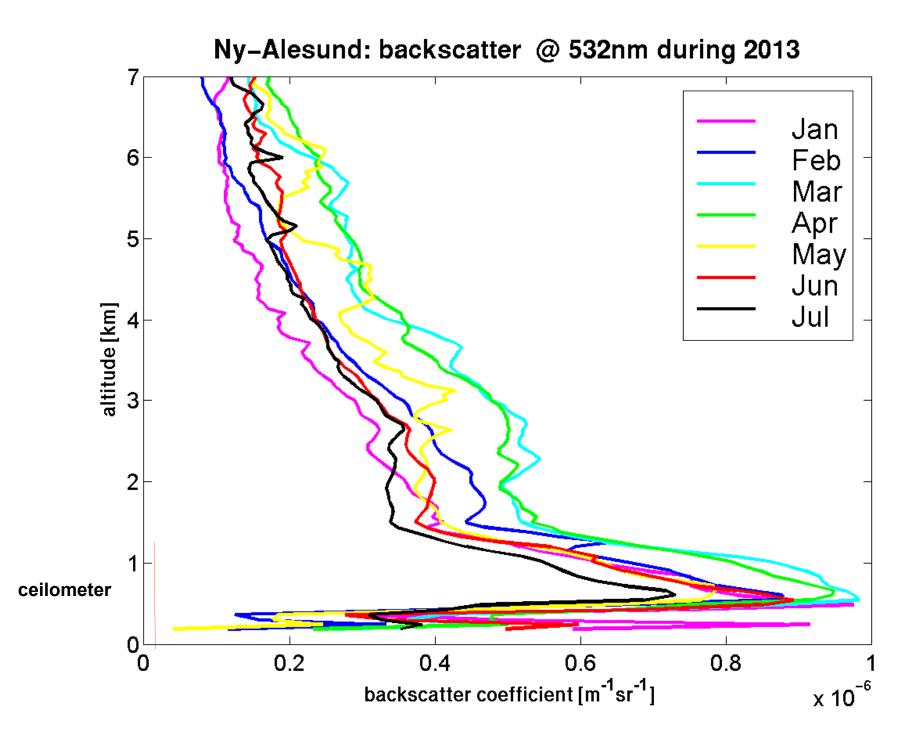
Measures:

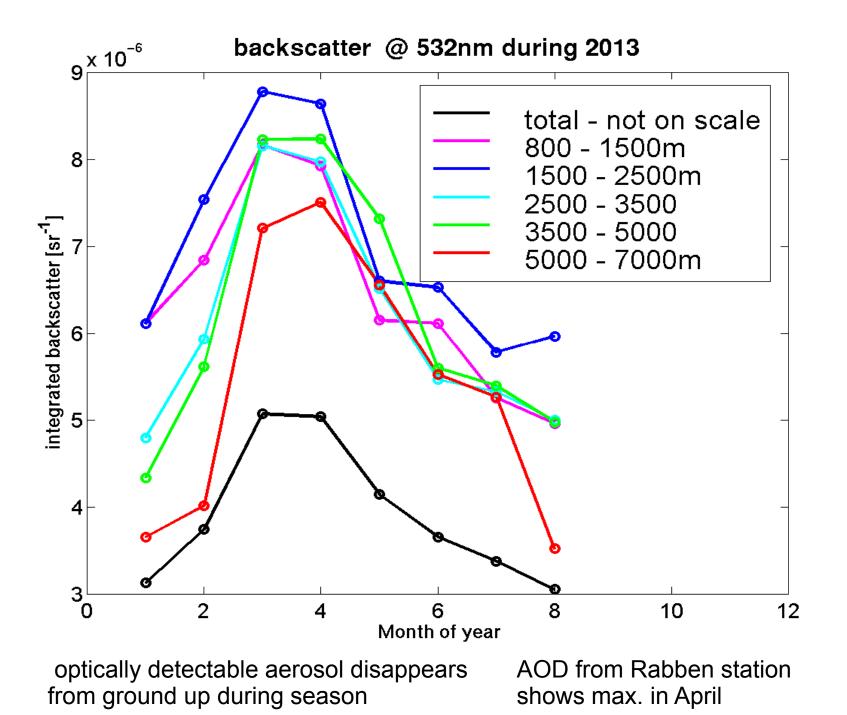
Backscatter: 355nm, 532nm, 1064nm Extinction: 355nm, 532nm (from N_2 Rot-Raman) Depolarisation: 355nm, 532nm Water vapor: 407nm, 660nm (from H_2O Rot-Raman)

Specs: Nd:Yag laser with 10W / color 70cm recording telescope Moveable aperture (diameter & position) for measurements in tropos- and stratosphere Starting at "Zeppelin altitude"

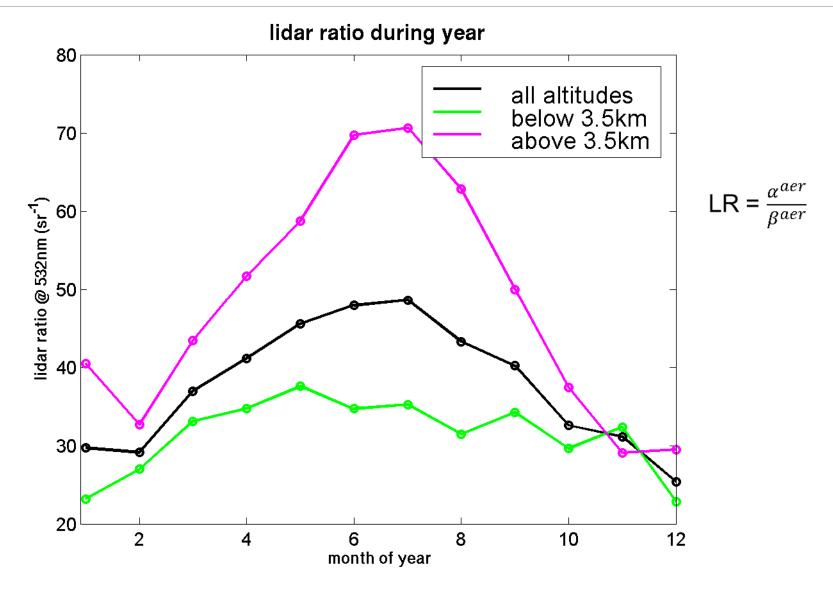
Used: aerosol in tropo & stratosphere, H₂O in (lower) troposphere





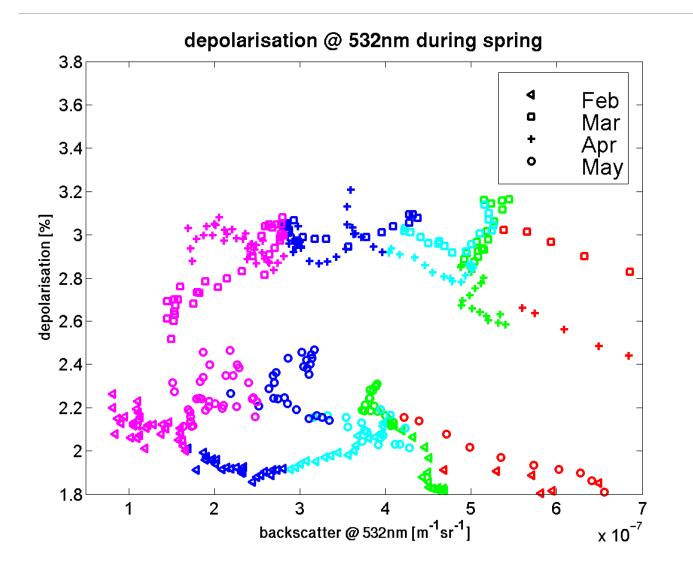










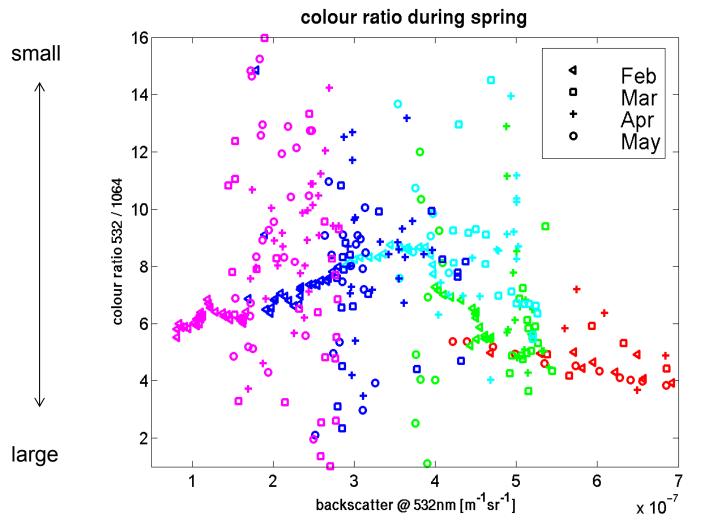




Particles more spherical outside haze season! (Mie better)









Size more uniform in Feb??



What does the aerosol lidar KARL deliver:

extensive quantities (dependent on aerosol number concentration):

backscatter (concentration, size, shape, refractive index)
extinction (concentration, size, shape, refractive index) !
(moreover specific humidity)

intensive quantities (not dependent on aerosol number concentration)

depolarisation $\delta = \frac{\beta_{\perp}}{\beta_{=}}$ (shape) [dipole moment] colour ratio $CR = \frac{\beta_{\lambda_{\perp}}}{\beta_{\lambda_{2}}}$ (size) $[\beta \sim \lambda^{A} -4 < A < 0]$ lidar ratio $LR(\lambda) = \frac{\alpha^{aer}}{\beta^{aer}}$ (index of refraction, size, shape)

Knowledge of δ , CR, LR allows a robust classification of aerosol type (dust, smoke, sea salt, cirrus...)

 \rightarrow it's about getting the intensive quantities!



Inverting lidar data:

Aim: estimate size distribution n(r) (r_{eff} , σ , N_0) and refractive index m from lidar data Assume spherical particles, Mie theory, efficiencies $Q_{ext/\beta}$ are known \rightarrow set of Fredholm integral equations for extinction & backscatter

$$\alpha(\lambda) = \int_{R_{\min}}^{R_{\max}} Q_{ext}(\lambda, r, m) \pi r^2 n(r) dr$$

$$\beta(\lambda) = \int_{R_{\min}}^{R_{\max}} Q_{\pi}(\lambda, r, m) \pi r^2 n(r) dr$$

Retrieval of n(r) from Q, α , β is an ill-posed Problem At least 2 α , 3 β needed

But:

Lidar is able to retrieve aerosol in accumulation mode: $0.1\mu < r < 1.2\mu$



Shortcomings of lidar data:

Phase function missing: only info around Φ =180 °

Refractive index challenging: $m = m_{real} + i \cdot m_{imag}$

 $m_{real} \sim scattering$ $m_{imag} \sim absorption$ but we only have β , α

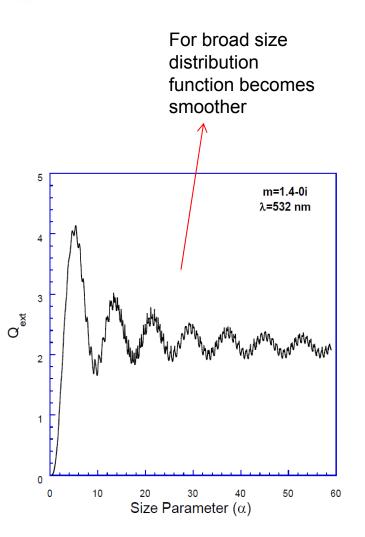
Weak absorption $\rightarrow \omega$ insecure

Only trustful info for accumu. mode: Aitken: interacction too small giant mode: Mie efficiency becomes flat

$$\alpha = \frac{2 \pi r}{\lambda} \iff r = \frac{\alpha \lambda}{2 \pi}$$

$$\alpha \in [1 ... 12], \lambda = 0, 5\mu \rightarrow r \in [\frac{1}{4\pi} ... \frac{3}{\pi}]\mu$$

conclusion: aerosol, cloud particles



Status KARL:



Ongoing long-term monitoring of aerosol

Strong interest in closure experiments

Interest in comparison with photometer(s): vertical vs. inclined column, local effects of aerosol, hygroscopic growth, role of summits

 \rightarrow aerosol – cloud – interaction

KARL good for particles in accumulation range

-Not in thick clouds, below, before and after clouds

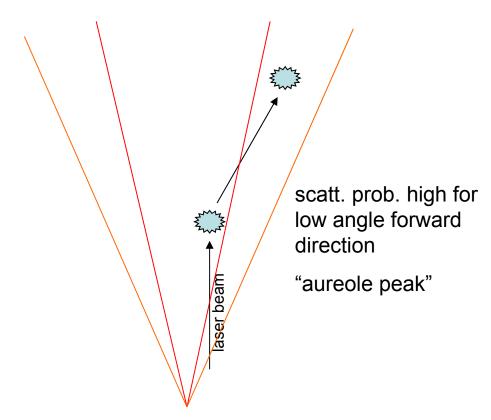
"Multiple field of view measurements"

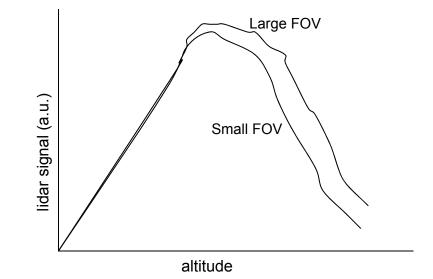




Sense of MFOV measurements

In an ideal world the count rate in a lidar increases with its field of view because more multiple scattered light will be collected.





A larger FOV should collect more light in and after a cloud. The aureole peak mainly results from large, crystal particles which cannot be analysed by Mie code inversions

telescope FOV

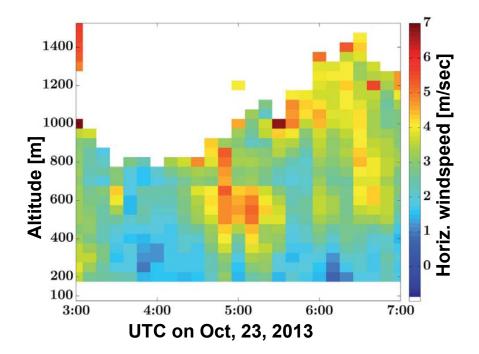
b) The wind lidar

A commercial instrument from Leosphere Measures the 3-dim wind with 50m / 10 min resolution from approx. 150m ... \pm 1200m (backscatter at 1.5µm, Doppler effect \rightarrow aerosol as tracer)

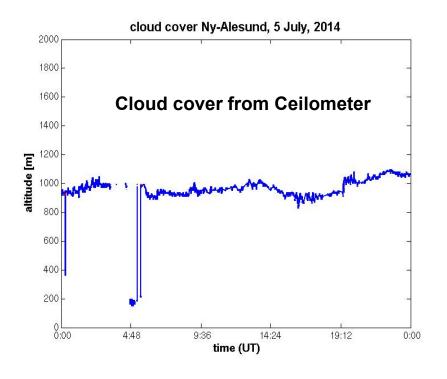
Master thesis S. Burgemeister: U,V components reliable Wind channeled along Fjord in lowest ±600m Passages of fronts detectable Several short living LLJ detected

Meanwhile: Also W component (vertical) But, particles still tracer?)



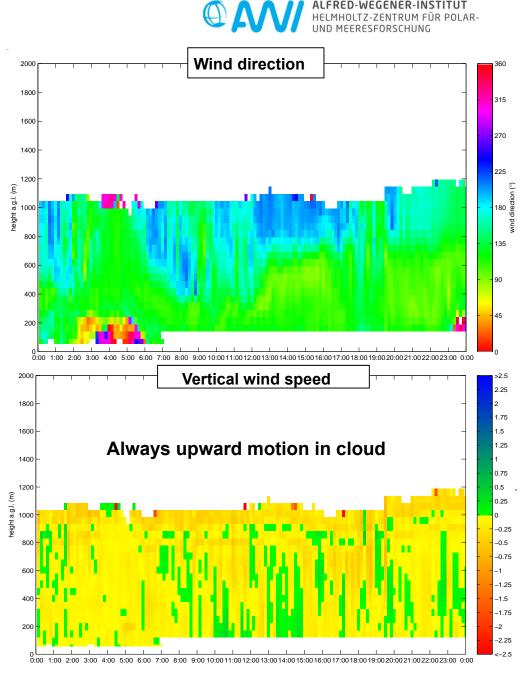


Reliability of the vertical wind (?) Case 5 July, 2014

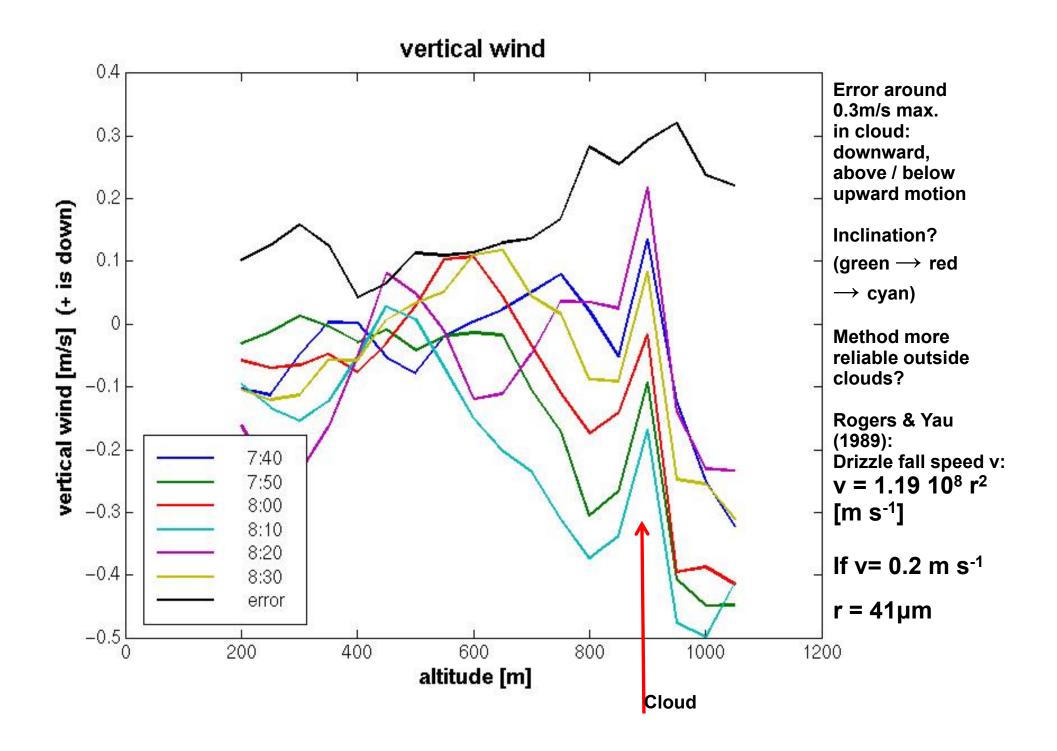


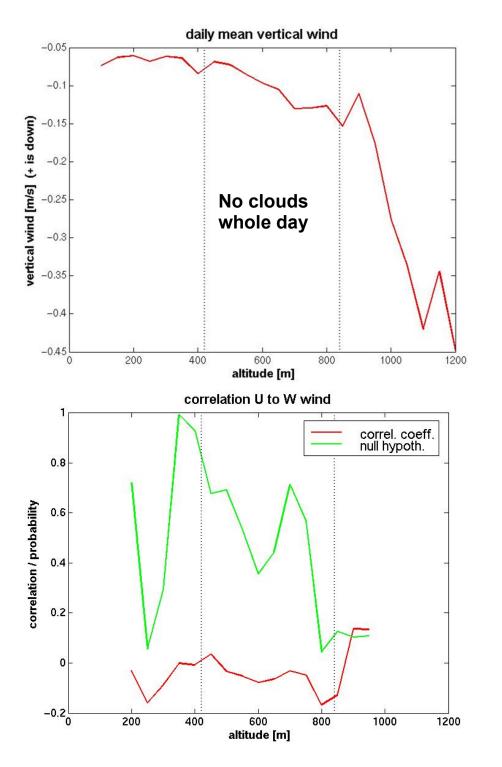
Persistent clouds around 1km altitude Vertical winds from -0.5 m/s (upward) To +0.5m/sec (downward)

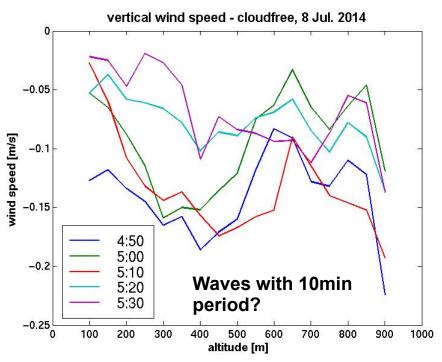
Time 7:40 – 8:30 constant cloud height 925m



ALFRED-WEGENER-INSTITUT HELMHOLTZ-ZENTRUM FÜR POLAR-







Summary wind lidar so far:

U,V wind are very reasonable

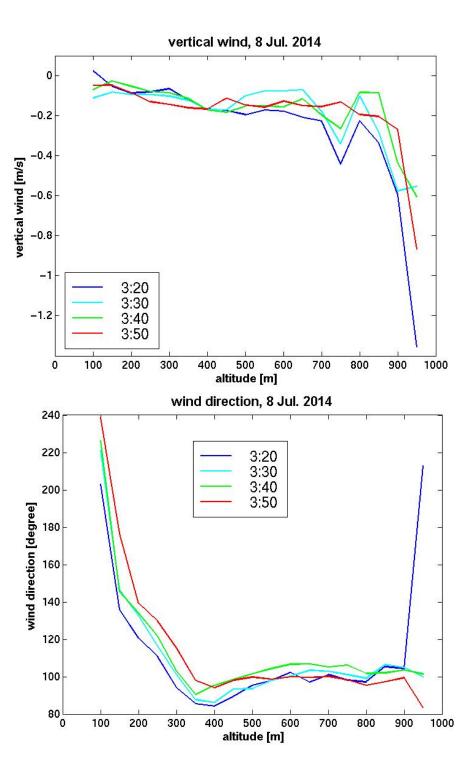
Vertical wind is evaluable, measurement precision (0.1 ... 0.3 m/s)

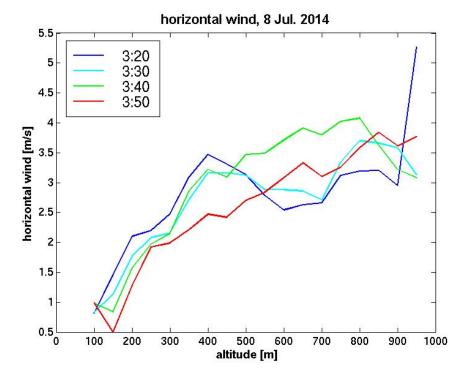
We see updraft in /around clouds

Droplets > 10µm have sedimentation rates that produce noticeable different velocities compared to air

Disintegration of a cloud 8 Jul. 2014

Ceilometer sees a cloud at 860m that suddenly disappears at 3:41.





Part c: ceilometer

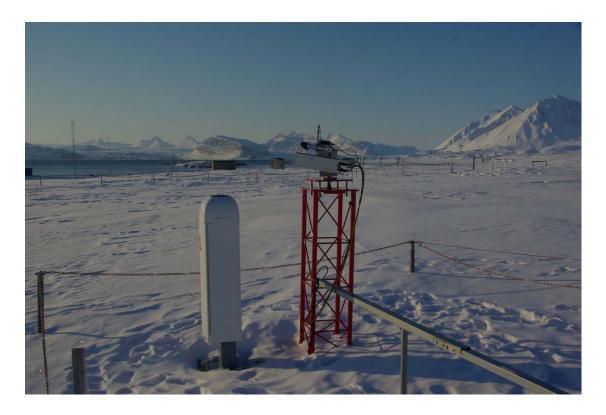


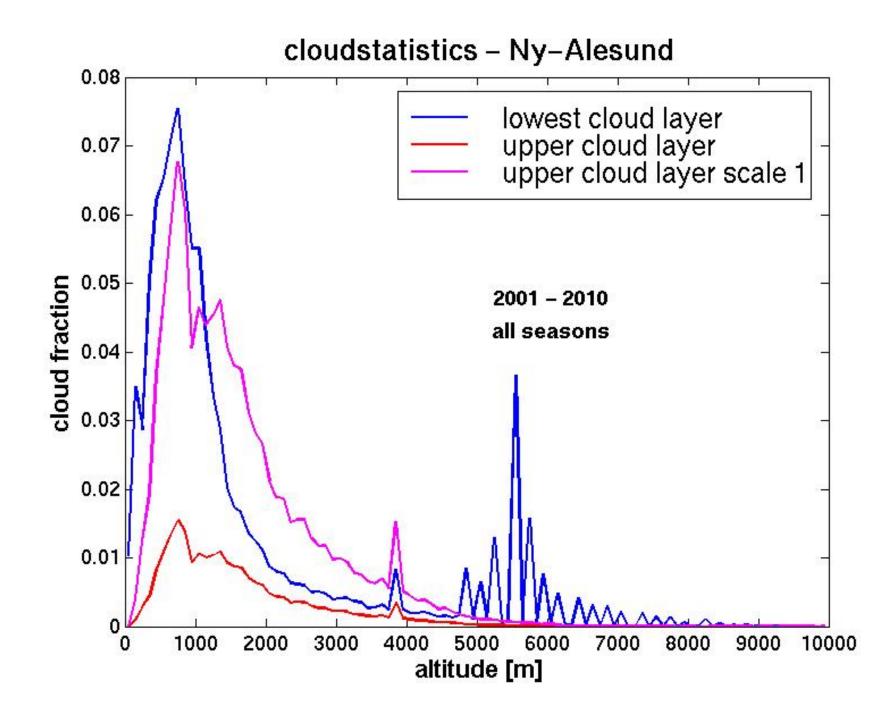
ALFRED-WEGENER-INSTITUT HELMHOLTZ-ZENTRUM FÜR POLAR-UND MEERESFORSCHUNG

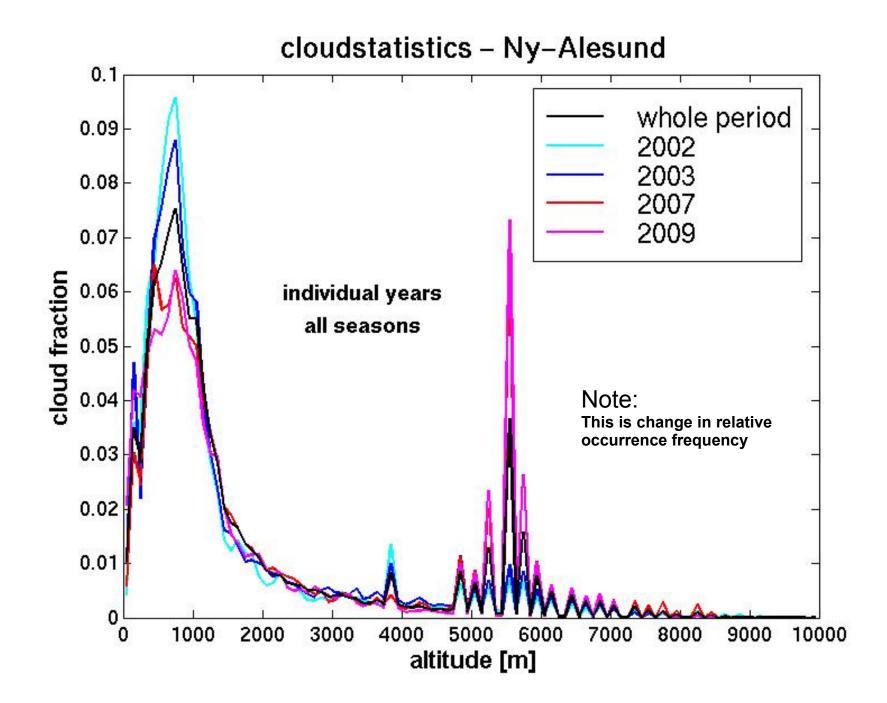
Always Vaisala 2000+ LD 25 LD 40 Since 2011 CL 51

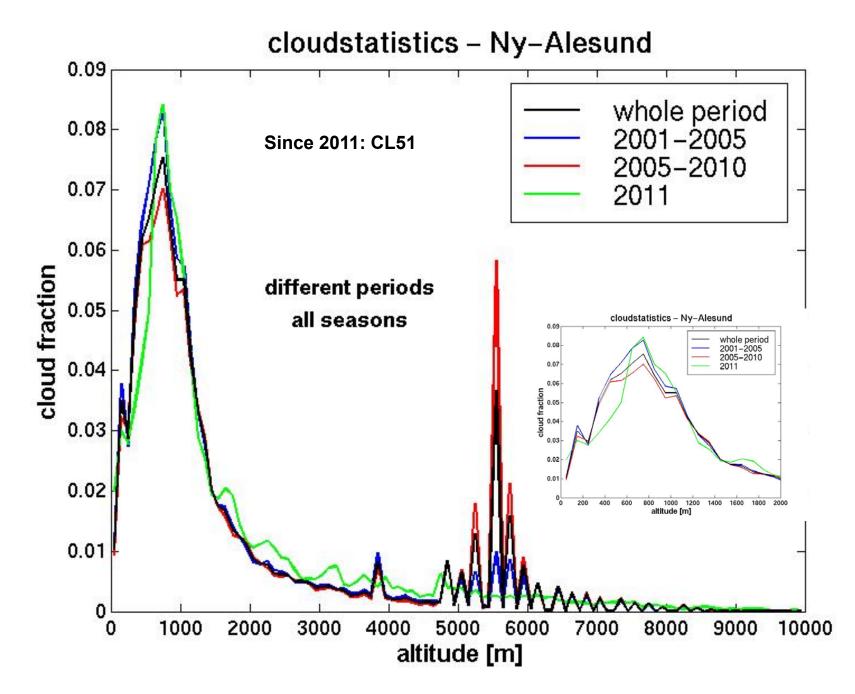
Use for cloud occurrence and backscatter (control overlapp for KARL)

 $\lambda = 910$ nm β useful up to 1km

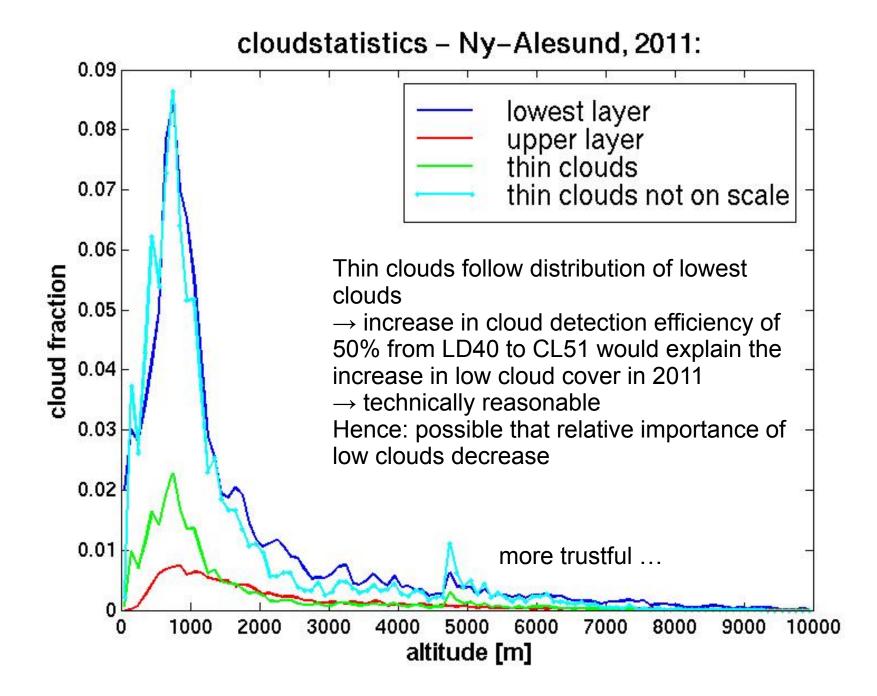


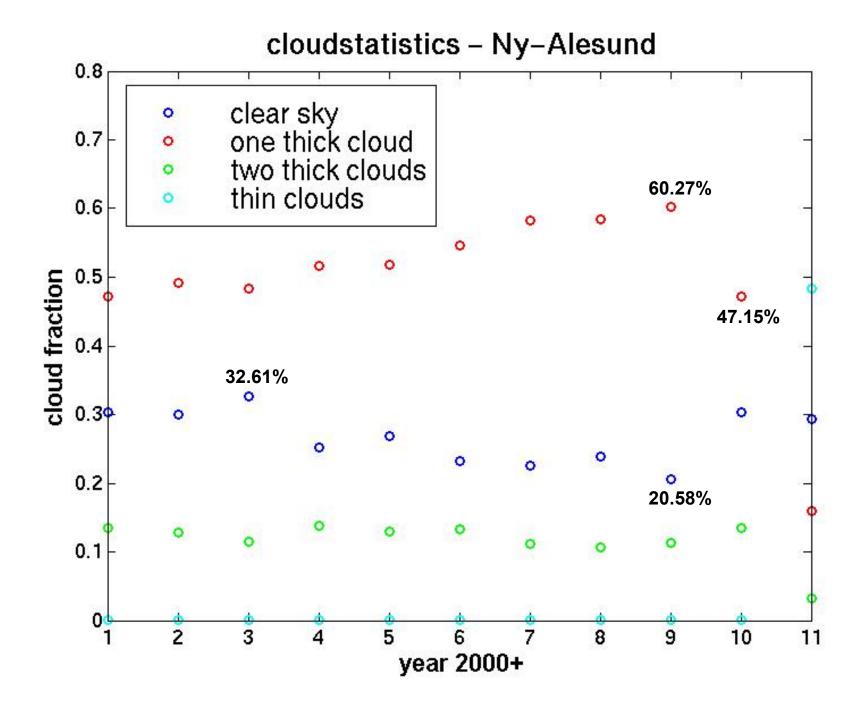






Are low clouds and ice clouds "anti-correlated"?







Cloud statistics depend on the quality of instrument (optics and software) Definition of "thin clouds" worst

CL 51 since 2011 much more powerful than precursor instrument

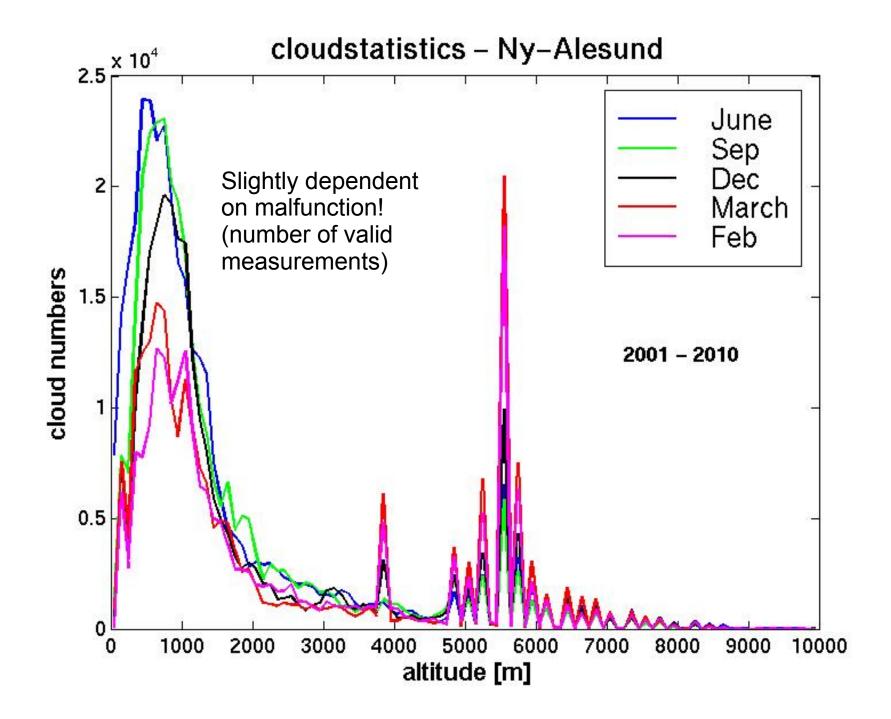
Can only consider years 2001 – 2010 easily (By the way: the Christoph Ritter foundation donates a nice German sausage for suggestions to obtain a homogeneous data set)

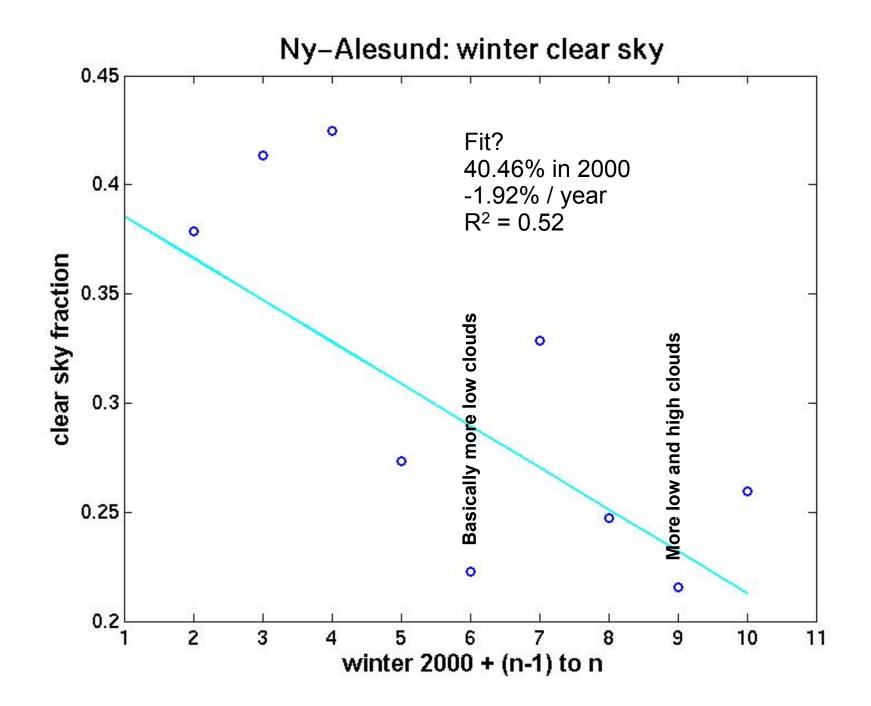
Low clouds around 750m dominate, their importance might decrease

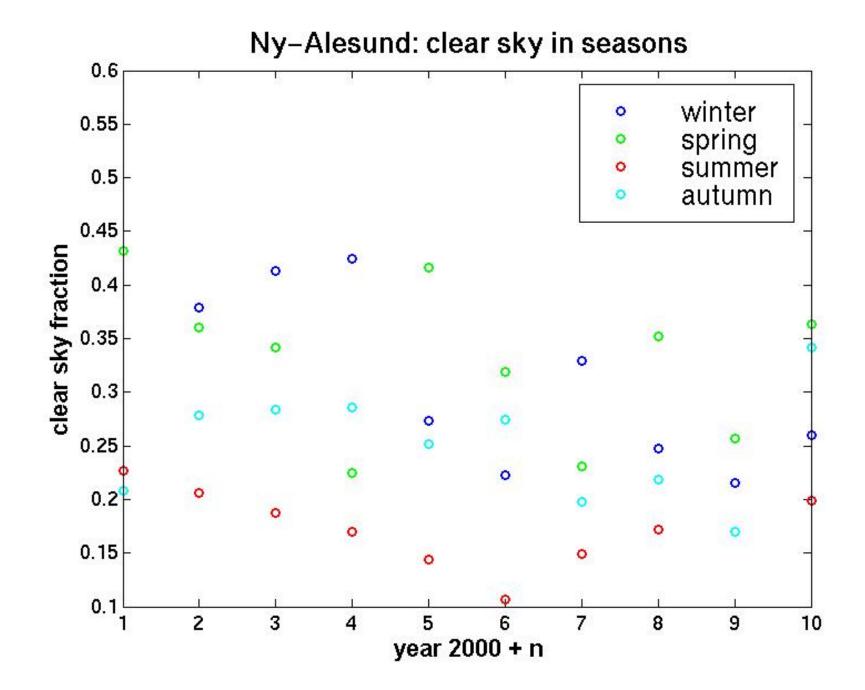
Low clouds and high clouds seem to be anti-correlated: high clouds seldom occur over low clouds (independent on instrument's power!)

Does fraction of clear days decrease?









Conclusions & evident things



Comp MPL to Ceilo: homogeneity

MPL or Ceilo with Windlidar & BSRN define interesting moments for cloud radar

Have to use KARL lidar "around" clouds as much as possible, +cloud radar: prove usefulness of remote sensing for clouds

For Ny, satellite val. elsewhere: need homogeneous equipment, same calibration, evaluation

KARL + photometers (Rabben, AWI) local and seasonal variability of haze, contribution to closure studies Clouds reduce range of understanding ...

