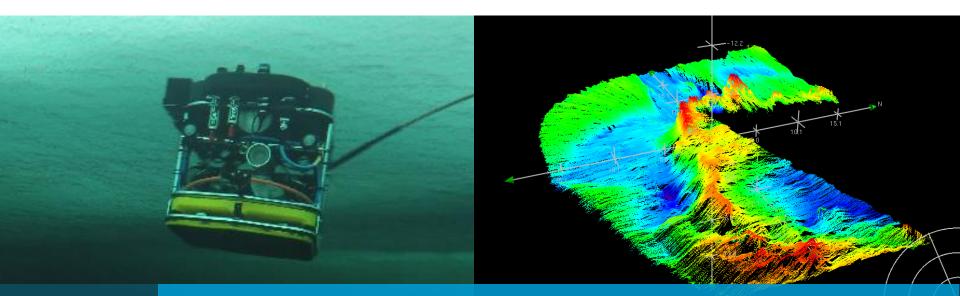
Christian Katlein, **Mario Hoppmann** Marcel Nicolaus, Veronica Coppolaro, Jakob Belter





First results from a new interdisciplinary robotic vehicle for under-ice research



#### What is an under-ice ROV (good for)?

1m

2m

3m

#### (ROV = Remotely Operated Vehicle)

2015

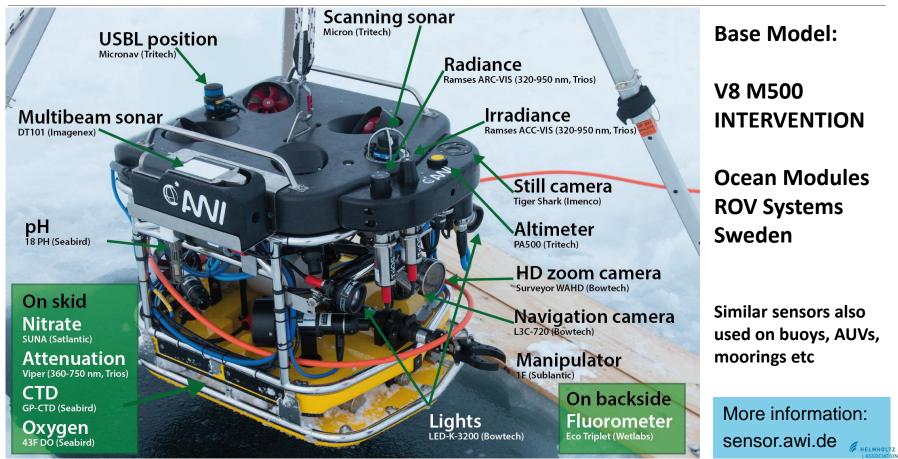
1980

investigate spatial variability

ALL DO

3x more

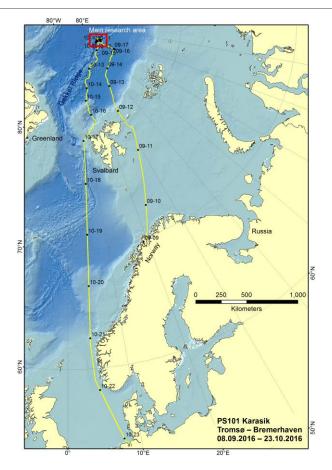
## Current ROV setup (Codename: BEAST)

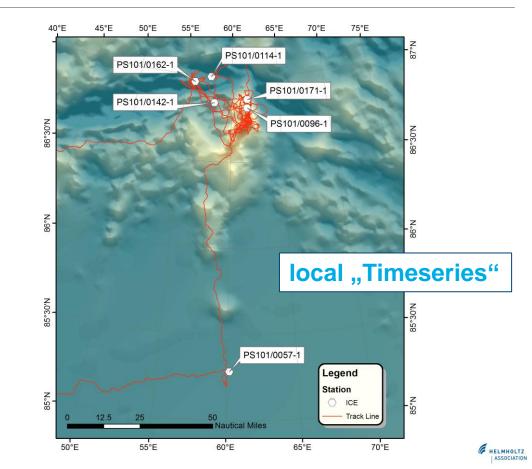


**@**AN/

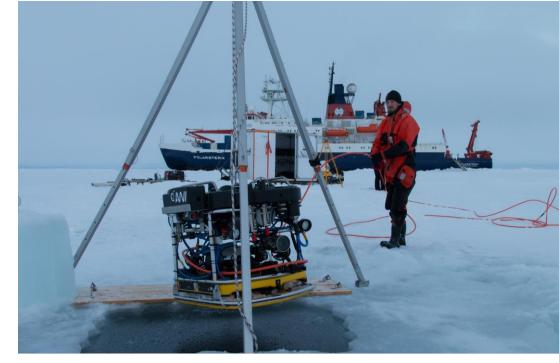
### 1st mission: PS101 (Sep-Oct 2016)







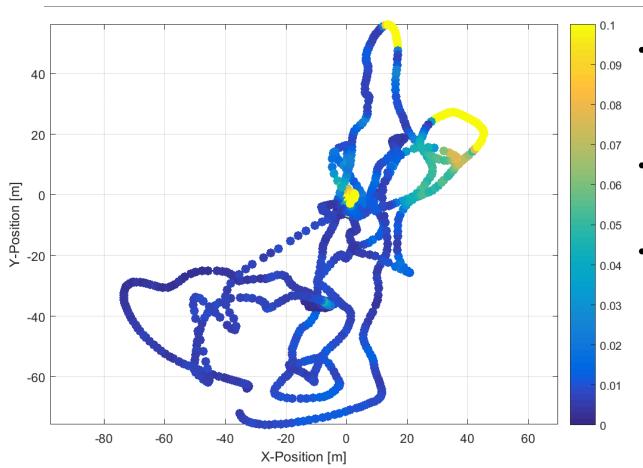
- **PS101 ROV work**
- 6 successful ROV ice stations in conjunction with other ice work
- All systems acquired data successfully
- Very complex system
- Ongoing data processing, archiving and evaluation





## **Upward looking camera**

## Light transmittance during freeze-up

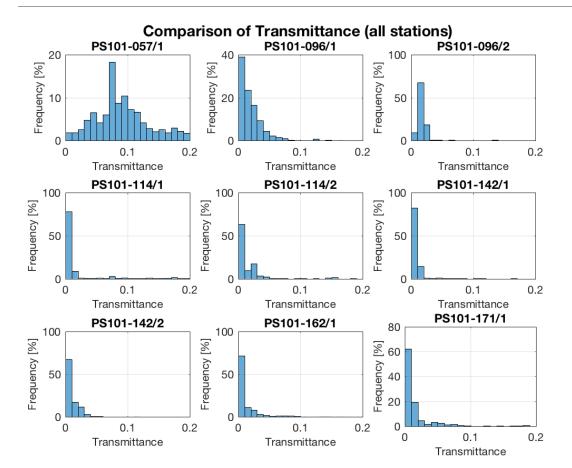


 yellow = open water over the floe edge (and access hole)

**O**M

- green = thin ice with higher transmittance
- blue = second year ice
  with low transmittance
  (snow covered)

# Light transmittance during freeze-up



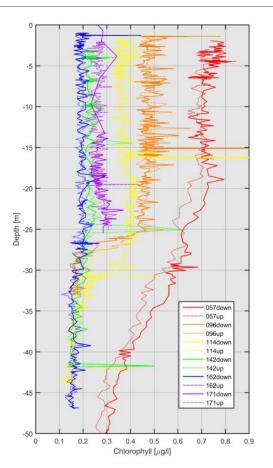
 Light transmittance decreases during freeze-up mostly due to snowfall

**@**AV/

 Late autumn: still light transmission through young ice and leads



## Highlight: under-ice autumn bloom

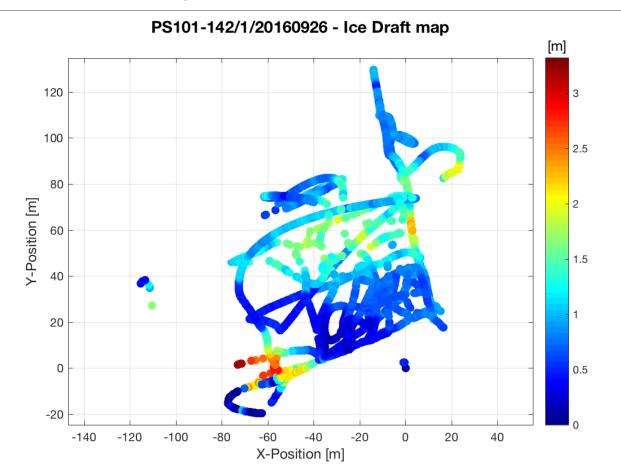


- Decreasing chlorophyll signal in the mixed layer
- Stunning zooplankton abundances under the ice (not shown)
- Unusually low sea ice concentration in the area

Rare observation in the central Arctic pack ice zone!

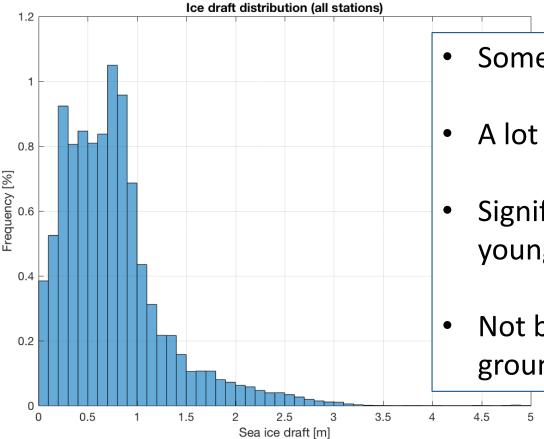
#### Sea ice draft maps from single beam sonar







#### Sea ice draft distribution from single beam sonar



- Some thick ice (ridges)
- A lot of FYI (mode at 0.8 m)
- Significant contribution of young, thin ice < 0.3 m</li>
- Not biased, unlike traditional, ground-based EM-methods



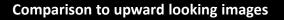
## Multibeam sonar

10.0-

5.0

15.1

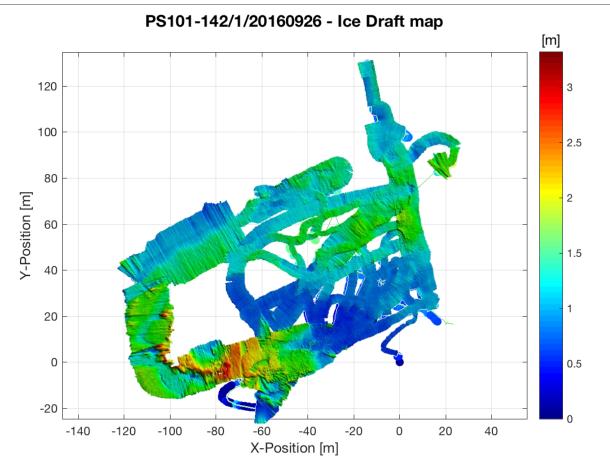
- 3D mapping
- Ice topography



### Floe scale maps of ice draft

#### Multibeam vs. Single beam sonar





HELMHOLTZ

## **Progress & future work**

- Data will be made publicly available on PANGAEA
- New AWI data portal (in development)
- Enable full vehicle functionality: Improve positioning system!
- Further payload to be included for next mission:
  - Water sampling bottle, ADCP (watertrack and under-ice turbulence)
  - Zooplankton camera (ROV-LOKI), Under-ice net (ROV-SUIT)

First full-scale science mission during Polarstern cruise with two week drift camp this spring (PS 106, May-June)



