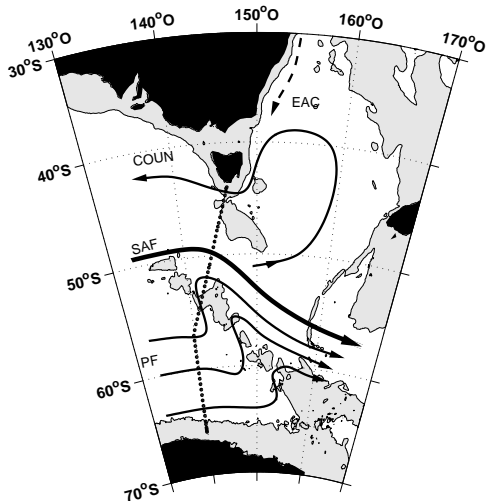


Deriving ocean surface currents from remote sensing techniques

Grit Freiwald, Martin Losch (AWI)
Silvia Becker, Wolf-Dieter Schuh (IGG - TG)

Hamburg, 12.06.2010

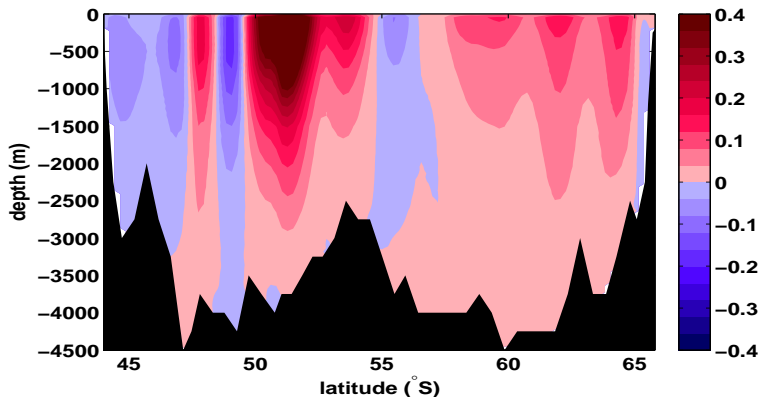
SR3 section



Assimilation:

- ▶ temperature
- ▶ salt
- ▶ velocities

Ocean model result

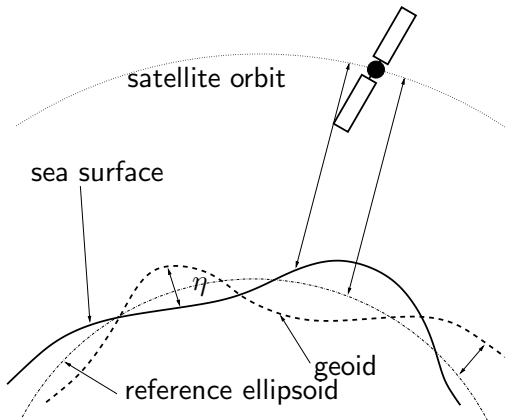


Transport across section: **159 ± 64 Sv**

Formal errors: Inverse of the Hessian of the cost function.

Mean dynamic topography

- ▶ geostrophic balance: $\frac{\partial \eta}{\partial x} = \frac{f}{g} \mathbf{v} \Rightarrow$ reference surface velocity
- ▶ $\eta = \mathbf{h} - \mathbf{N}$



Problems with the geoid!

- ▶ geoid models describe short scales not sufficiently for oceanography
- ▶ omission error is generally neglected
=> underestimation of the geoid model error
- ▶ “higher” accuracy => larger formal error
- ▶ considering omission error => “complete” geoid models

**Is it possible to improve the ocean models
by assimilating MDT?**

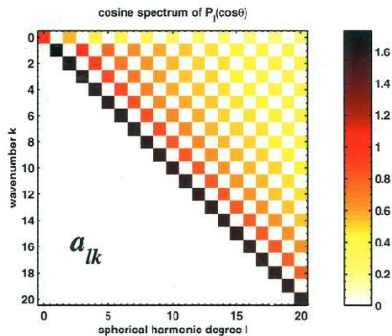
Principle for omission error problems

Homogeneous, isotropic covariance function for geoid model

$$C(\psi) = \sum_{l=0}^L p_l P_l(\cos \psi) = \sum_{l=0}^L p_l \sum_{k=0}^l a_{lk} \cos k\psi = \sum_{k=0}^L c_k \cos k\psi$$

with the (Fourier-) coefficients

$$c_k = \sum_{l=k}^L p_l a_{lk}$$



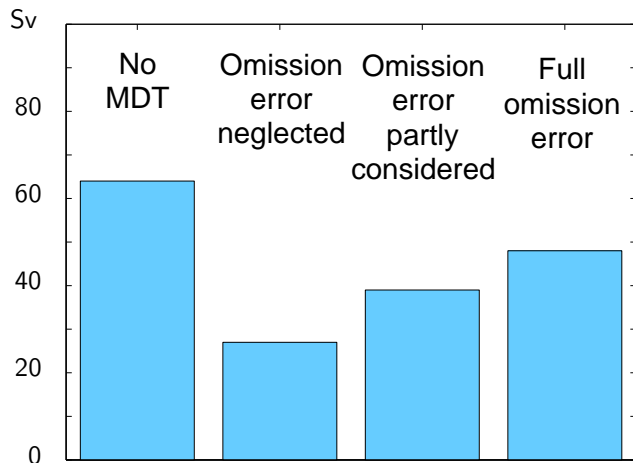
Ocean model parameters

Free to choose:

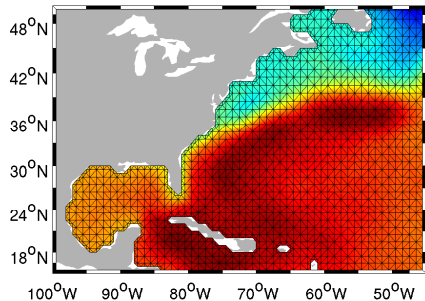
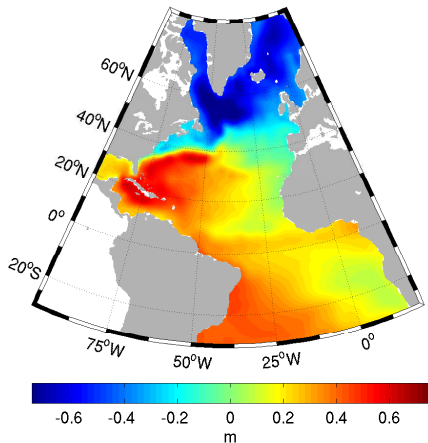
- ▶ discretization method
- ▶ number of iterations
- ▶ bottom (reference) velocities
- ▶ roughness parameters
for salinity, temperature, horizontal velocities
- ▶ prior error estimations

↔ Transport across section: **174 ± 48 Sv**

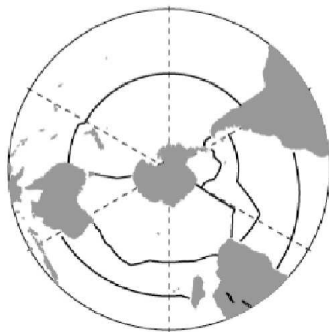
Transport error estimates



Stationary 3D model: IFEOM



Inverse box model for the Southern Ocean



e.g. Sloyan and Rintoul (2001),
Losch, Sloyan, Schröter and Sneeuw (2002)

Ice drift algorithm

$$\begin{bmatrix} \bar{c}_u \\ \bar{c}_v \end{bmatrix} = \begin{bmatrix} \bar{U} \\ \bar{V} \end{bmatrix} - F \cdot \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} \bar{u} \\ \bar{v} \end{bmatrix}$$

Turning angle: $\theta = \arctan \left[\frac{\sum u'V' - \sum v'U'}{\sum u'U' + \sum v'V'} \right]$

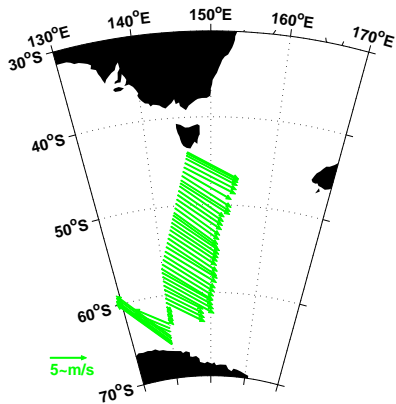
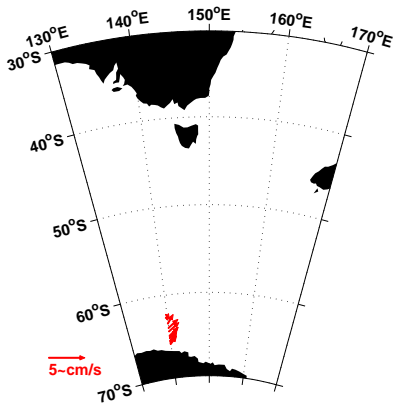
Speed reduction factor:

$$F = \frac{\cos \theta \sum u'U' + \sin \theta \sum v'U' - \sin \theta \sum u'V' + \cos \theta \sum v'V'}{\sum u'^2 + \sum v'^2},$$

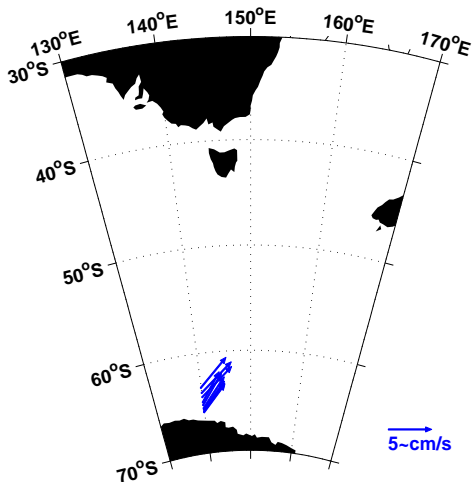
$$u' = u - \bar{u} \quad \text{etc.}$$

(N. Kimura: Sea Ice Motion in Response to Surface Wind and Ocean Current in the Southern Ocean, JMSJ 2004.)

Ice drift and wind data



Resulting ocean surface currents



Mass transport across section:

173 ± 46 Sv

Summary

Mass transport across section for the 3 cases:

Ocean model only: **159 ± 64 Sv**

Ocean with dynamic topography: **174 ± 48 Sv**

Ocean with drifting sea ice: **173 ± 46 Sv**

Thank you for your attention!

? *Questions* ?