GLOBCOVER 2009

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ABSTRACT

GlobCover 2009 has been processed from MERIS Full Resolution data co llected from 1 Jan uary 2 009 to 31 December 2009. The data set coverage is discussed. The GlobCover pr ocessing f acts ar e highlighted. The validation and q uality assessment of the final products (Land Co ver follo wing LCCS from FAO) an d composites is also d iscussed. An in dependent qu ality check will be p erformed b y JRC, wh ile a syste matic validation is org anized by the Un iversité Catholique de Louvain u sing an in ternational tea m of 16 land cov er experts.

1. INTRODUCTION: WHY STILL GLOBCOVER?

GlobCover v2.2 was a m ajor success for E SA and its partners [1]. The in itiative was launched in the framework of the Data User Element (DUE) and concluded in October 2008 with the creation of the sharpest so far (300 m.) global land cover map, having an LCCS-compatible legend with 22 informational classes (see [2]). The use r community of GlobCover counts 4800 registered users coming from a large variety of di sciplines, which proves the need a nd interest for global land cover products.

In parallel, it h as been released that regular upd ate of land cover information is of major importance, towards a better understanding of the ongoing processes which affect 1 and cove r/use dynamics [3]. Un der t his perception, in the fram ework of GlobCo ver ESA highlighted the need to built and demonstrate the use of systems which are able t o process large amount of data and pr oduce gl obal informational maps without any major human intervention. This will enable future plugand-get chains and facilitate routine production of maps. As a result, the continuation of GlobCover to produce an update of the global l and cover map for 2009 has been decided.

Based on the experience gained during GlobCover v2.2, as well as the infrastructure which has been built, ESA runs internally GlobCover 2009 in partnership with JRC and Université Cath olique de Lou vain (UCL). Below we present the new initiative.

2. MERIS INPUT DATA ACQUISITION

The main data source of the GlobCover 2009 project are MERIS 30 0 m. Fu ll Reso lution Fu ll Swath (FR S) products. T he acq uisitions cover a period from 1 st January 2009 to 31 st December 2009. MER IS FRS are not acquired systematically, therefore ESA had to make effort to cov er t he land m ass with su fficient acquisitions, particularly in areas outside the ARTEMIS mask (e.g. East part of South America, Central America, Korean Peninsula, Pat agonia). Fig. 1 provides a gl obal overview of th e acqu isitions and th e resulted v alid cloud-free o bservations. O ur calculations indicate that 99% of the land (excluding Antarctica) is covered by at least one MERIS FRS image.



Figure 1. Up: ME RIS F RS acq uisition density for 2009. Down: Number of valid observations.

3. THE GLOBCOVER SYSTEM

The Gl obCover sy stem consi sts of three components [3]: i) the Glob Cover software, ii) the execution environment and iii) the hardware. The system ingested approximately 20 TB s of zipped M ERIS FR S data acquired during 2009.

3.1. Software

The GlobCover software includes two basic processing sub-systems: i) t he s o-called ' pre-processing' m odule and, i i) t he cl assification m odule. T he fi rst one implements a pre -processing c hain w hich i mports MERIS FRS Lev el 1B data an d ex tracts Lev el 3 Mosaics, which are then feed the classification process. The p re-processing c hain st arts with th e AMORGOS tool, w hich g eometrically corrects the images. It ha s been already shown from previous investigations of [4] that AM ORGOS ach ieves very satisfying results with relative and absolute geo-location RMSE far b elow the requirement of 150 m. (i.e. ~50 m. relative and ~80 m. absolute RMSE).

The following processing st ep im plements a chain of corrections to diminish the influence of the atmosphere and calc ulate Surface Directional Reflecta nce (SDR). The correction algorithm s include: cloud and snow

pixels sc reening and flagging, gase ous abs orption correction, R ayleigh scatte ring, ae rosol co rrection (based on MERIS RR LARS for 20 09), sm ile correction. Finally, the d irectional reflectance products are projected in Plate-Carrée and s ubset into $5^{\circ}x5^{\circ}$ tiles according to the GlobC over schema (see [5]). In orde r to minimise the bi-directional reflectance effects we use a si mple co mposition av eraging (BRDF correction). Moreover, sea sonal m osaics are c reated by avera ging the refl ectance du ring pa rticular pe riods, which ha ve been tuned in order to assist in the classification.

The classification subsystem runs independently for 22 equal-reasoning areas, which have been created taking into account bio-climatic criteria, in order to increase the spect ral differentiation am ong cl asses. I n t he beginning an unsupervised ISODATA algorithm is used to classify spectrally the im ages, while afte r phenological param eters per pi xel are e xtracted. T he subsequent cl ustering al gorithm gro ups classes wi th similar characteristics creating spectro-temporal classes. Then the product is being labelled by using a reference dataset (GlobCover v2.2 will be used to lab el the new product) and finally, the result has to be checked and post-processing (e. g. re -labelling) m ight be appl ied whenever needed.

3.2. Execution Environment

The Gl obCover sy stem has a modular design, which enables clear separation bet ween the s ubsystems and

their components. A stand ardised i nterface is u sed to link and execute individual modules.

A database-backed catalogue handles data provision to the p re-processing a nd cl assification s ubsystems and deals with the storage and retrieval of input, output and auxiliary data. The database acts as a cen tral communication c omponent, facilitating independent verification tasks, as well as integration testing.

The system h andles rou tines that h ave b een written in multiple programming l anguages a nd allows al so integration of external programs, like AMOR GOS, BEAM modules or ENVI routines [6].

3.3. Hardware

The h ardware components of t he previous Gl obCover project ha ve been received in ESRIN and whenever needed were up dated wi th new pa rts. The storage capacity is 5 4 Tb , wit h 52 CPUs (at 2.3 GHz). A schematic repr esentation of the Gl obCover sy stem is given in Fig. 2.



Figure 2. Schematic representation of the GlobCover system installed in ESRIN.

4. CURRENT STATE

In the 24th of June 2010, the processing of the MERIS FRS L1B input data has finished and two bi-products have been produced: i) an An nual Gl obCover 2 009 Composite, an d i i) si x B i-monthly C omposites. Our initial assess ment sho wed that th e results are of go od quality when the valid observations are sufficien t. The composition process has created some artefacts in some areas, where the observations a re less than ~ 30 . The products will be freely av ailable to the users with a simple registration, through the Ionia GlobCover portal (see http://www.esa.int/due/ionia/globcover). Th rough Ionia use rs will have access to the Gl obCover 2009 composites, cr opped i n 5 °x5° tiles an d p rojected in Plate-Carrée. The tiles are released in Hierarchical Data Format -EOS 2 (HDF). An example of the Annual composite mosaic is given in Fig. 3.



Figure 3. Annual GlobCover 2009 mosaic (MERIS FR 300m).

Currently ESA 's effort is c oncentrated on the production of the GlobCover 2009 Global Land Cover Map. Un iversité Catholique de Louv ain (UCL) will take over the validation of the product. A we b-based validation t ool has been created by UCL, to assist in the process and a global network of land cover experts will support the validation exercise as well [5].

5. CONCLUSION

The importance of GlobCover 2009 initiative relies on the fact that it will de monstrate the capacity to frequently up date t he gl obal l and co ver map. With GlobCover 2009 ESA will prov ide not on ly the most detailed global land cover map so far, but also the most recent and updated [7]. Attention will be given on the integrity of the v alidation exercise, which is managed by an experienced team of UCL. Future news regarding the initiative and the final product will b e announced on Ionia Server, which is the main distribution point and through the next GlobCover Newsletter.

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