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Building a Scalable Ensemble Data Assimilation System for Coupled Models

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Motivation

How to build an efficient data assimilation system – in a simple way?

- 1. Extend model to integrate an ensemble
 - mainly: adapt parallelization
- 2. Add analysis step to the model
 - just an update in between time steps

Here discussed for a coupled model



Example: ECHAM6-FESOM (AWI-CM)



D. Sidorenko et al., Clim. Dyn. 44 (2015) 757

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PDAF: A tool for data assimilation

Parallel Data Assimilation Framework

PDAF - Parallel Data Assimilation Framework

- a program library for ensemble data assimilation
- provide support for parallel ensemble forecasts
- provide fully-implemented & parallelized filters and smoothers (EnKF, LETKF, NETF, EWPF ... easy to add more)
- easily useable with (probably) any numerical model (applied with NEMO, MITgcm, FESOM, HBM, TerrSysMP, …)
- run from laptops to supercomputers (Fortran, MPI & OpenMP)
- first public release in 2004; continued development
- ~250 registered users; community contributions

Open source: Code, documentation & tutorials at

http://pdaf.awi.de

L. Nerger, W. Hiller, Computers & Geosciences 55 (2013) 110-118

Parallel Data Assimilation Framework

Assumption: Users know their model

→ let users implement DA system in model context

For users, model is not just a forward operator

→ let users extend they model for data assimilation

Keep simple things simple:

- Define subroutine interfaces to separate model and assimilation based on arrays
- No object-oriented programming (most models don't use it; most model developers don't know it; not many objects would be involved)
- Users directly implement observation specific routines (no indirect description of e.g. observation layout)



Ensemble Filter Analysis Step



Logical separation of assimilation system



- ← Explicit interface
- --- Indirect exchange (module/common)

Nerger, L., Hiller, W. Software for Ensemble-based DA Systems – Implementation and Scalability. Computers and Geosciences 55 (2013) 110-118



Parallel Data

Assimilation Framework

Extending a Model for Data Assimilation

Parallel Data Assimilation Framework



Framework solution with generic filter implementation



Simple Subroutine Interfaces

Example: observation operator

```
SUBROUTINE obs_op(step, dim, dim_obs, state, m_state)
IMPLICIT NONE
ARGUMENTS:
INTEGER, INTENT(in) :: step ! Current time step
INTEGER, INTENT(in) :: dim ! PE-local dimension of state
INTEGER, INTENT(in) :: dim_obs ! Dimension of observed state
REAL, INTENT(in) :: state(dim) ! PE-local model state
REAL, INTENT(inout) :: m_state(dim_obs) ! Observed state
```



Problem reduces to:

- 1. Insert assimilation subroutine calls to model codes
- 2. Configuration of parallelization (MPI communicators)
- 3. Implementation of compartment-specific user routines and linking with model codes at compile time



2-level Parallelism



- 1. Multiple concurrent model tasks
- 2. Each model task can be parallelized
- Analysis step is also parallelized
- Configured by "MPI Communicators"

2 compartment system – strongly coupled DA



Configure Parallelization – weakly coupled DA



Logical decomposition:

- Communicator for each
 - Coupled model task
 - Compartment in each task (init by coupler)
 - (Coupler *might want to split* MPI_COMM_WORLD)
 - Filter for each compartment
 - Connection for collecting ensembles for filtering
- Different compartments
 - Initialize distinct assimilation parameters
 - Use distinct user routines



Example: ECHAM6-FESOM



1.852 executables ECHAM and FESOM – do all coding twice

- add subroutine call into both models
- adapt model communicator (distinct names in the models)
- replace MPI_COMM_WORLD in communication routines for fluxes

In OASIS-MCT library

- Replace MPI_COMM_WORLD in OASIS coupler
- Let each model task write files with interpolation information



Strongly coupled: Parallelization of analysis step



We need innovation: $\mathbf{d} = \mathbf{H}\mathbf{x} - \mathbf{y}$

Observation operator links different compartments

- Compute part of **d** on process 'owning' the observation
- 2. Communicate **d** to processes for which observation is within localization radius



Execution times (weakly-coupled, DA only into ocean)



 Likely caused by MPI-communication (e.g. no optimal distribution of programs over compute nodes/racks)

Summary

- Status of AWI-CM/PDAF: ready to be used (Postdoc just started)
- Software framework simplifies building data assimilation systems
- Efficient online DA coupling; minimal model code changes
- Setup of data assimilation with coupled model
 - 1. Configuration of communicators
 - 2. Add routines for initialization & analysis step
 - 3. Implementation of case-specific user-routines
- Size of computing problem and communication layout might lead to tuning requirements

Thank you !

Lars.Nerger@awi.de - Building EnsDA System for Coupled Models

Current algorithms in PDAF

PDAF originated from comparison studies of different filters

Filters and smoothers

- EnKF (Evensen, 1994 + perturbed obs.)
- ETKF (Bishop et al., 2001)
- SEIK filter (Pham et al., 1998)
- ESTKF (Nerger et al., 2012)
- NETF (Toedter & Ahrens, 2015)

All methods include

- global and localized versions
- smoothers

Not yet released:

Parallel Data

Framework

- serial EnSRF
- particle filter
- EWPF



References

- http://pdaf.awi.de
- Nerger, L., Hiller, W. Software for Ensemble-based DA Systems – Implementation and Scalability. Computers and Geosciences 55 (2013) 110-118
- Nerger, L., Hiller, W., Schröter, J.(2005). PDAF The Parallel Data Assimilation Framework: Experiences with Kalman Filtering, Proceedings of the Eleventh ECMWF Workshop on the Use of High Performance Computing in Meteorology, Reading, UK, 25 - 29 October 2004, pp. 63-83.